Structural signatures of the unjamming transition at zero temperature

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We study the pair correlation function g(r) for zero-temperature, disordered, soft-sphere packings just above the onset of jamming. We find distinct signatures of the transition in both the first and split second peaks of this function. As the transition is approached from the jammed side (at higher packing fraction) the first peak diverges and narrows on the small-*r* side to a δ function. On the high-*r* side of this peak, g(r) decays as a power law. In the split second peak, the two subpeaks are both singular at the transition, with power-law behavior on their low-*r* sides and step-function drop-offs on their high-*r* sides. These singularities at the transition are reminiscent of empirical criteria that have previously been used to distinguish glassy structures from liquid ones.

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I. INTRODUCTION

It is only natural to suspect that the dramatic dynamical arrest that occurs as a liquid is cooled into a glass must be accompanied by a signature in the underlying atomic arrangements. However, the atomic configurations in the liquid and glass are strikingly similar to one another. Over the years, the challenge to identify a subtle structural difference between the two states has led to the proposal of several empirical criteria [1–3]. In this paper, we reconsider an old idea, due to Bernal [4], of using static sphere packings to gain insight into the structure of amorphous systems [5–10]. We find that, with decreasing density, the structure of such packings changes distinctly as they unjam.

It is particularly revealing to study static packings of spheres interacting via a finite-ranged, purely repulsive potential. There is a fundamental change in the mechanical properties in such systems, reminiscent of the glass transition [11], as the packing fraction ϕ is varied across a well-defined unjamming-jamming transition at ϕ_c , which was found to coincide with the value of random close packing ≈ 0.64 [12,13]. Above ϕ_c the system has nonzero static shear and bulk moduli, while below ϕ_c it costs no energy to shear or compress the system by an infinitesimal amount. Moreover, the unjamming transition in many ways resembles a critical point [12–20], with many quantities, including a diverging length scale, behaving as power laws as the transition is approached from higher density. Here we show that the unjamming transition exhibits clearly identifiable structural signatures associated with diverging quantities, even though both the jammed and the unjammed states are disordered. These structural characteristics are echoed in some of the empirical criteria [1–3] that have previously been proposed for the glass transition.

The simulations reported here are for monodisperse, soft spheres of diameter σ that interact through the potential $V(r) = (V_0/\alpha)(1-r)^{\alpha}$, for r < 1, and V(r) = 0 when $r \ge 1$. Here, r is the center-to-center separation between two particles, measured in units of σ . We have studied both the harmonic, α =2, and the Hertzian, α =2.5, cases. Particles are defined to be in contact if they overlap. Our three-dimensional systems consist of $1024 \le N \le 10\,000$ spheres in periodic, cubic simulation cells. To enable a systematic study of the approach to the unjamming transition, we employ conjugate-gradient energy minimization [21] to obtain *T*=0 configurations at various packing fractions ϕ . We average over ensembles of configurations at the same distance from the transition point, i.e., at the same values of $\Delta \phi \equiv \phi - \phi_c$, which is equivalent to averaging over systems with the same pressure [12,13].

Structural signatures of jamming are more evident [13] in the pair correlation function g(r) than in the structure factor S(k), even though the two functions are simply related by a Fourier transform. We therefore focus on the structural characteristics that signal the approach of the zero-temperature transition from the jammed side, through a detailed analysis of g(r) computed with extraordinary resolution. In particular, we study two features of g(r) that undergo dramatic changes at the unjamming transition: the first peak and the split second peak (i.e., the two subpeaks that merge with increasing temperature to become the second peak in a typical dense liquid). A plot of g(r) is shown in Fig. 1 above the jamming transition.



FIG. 1. The pair correlation function g(r) vs r at two extreme values of $\Delta \phi \equiv \phi - \phi_c = 10^{-6}$ (dotted line) and 10^{-1} (solid line). The maximum value of the first peak height is higher and its width narrower for the lower value of $\Delta \phi$. For $\Delta \phi = 10^{-6}$, the first-peak maximum is approximately 10^6 , far beyond the scale of the graph.



FIG. 2. The height $g(r_{\text{peak}})$ (top panels) and the left-hand width w_L (bottom panels) of the nearest-neighbor peak of g(r), over several orders of magnitude of $\Delta \phi$, for monodisperse spheres with purely repulsive (a) harmonic spring and (b) Hertzian interactions.

II. FIRST PEAK OF g(r)

The dominant feature in g(r) is the first tall, sharp peak at r_{peak} (Fig. 1). Precisely at the jamming threshold, $\Delta \phi \equiv \phi - \phi_c = 0$, this peak is a δ function at $r_{\text{peak}} = 1$; g(r) is precisely zero for r < 1 and has a power-law tail extending to r > 1. The weight under the δ function is the coordination number at contact, Z_{contact} . (As we discuss below, Z_{contact} is a few percent less than the isostatic coordination number $Z_c = 2d = 6$ for our (d=3)-dimensional systems [12,13,22].) For $\Delta \phi > 0$, there is some overlap between particles so that the δ -function peak broadens and shifts to $r_{\text{peak}} < 1$, similar to the behavior of compressed emulsions [23]. The broadening produces a tail extending to $r < r_{\text{peak}}$ that disappears in the limit where $\Delta \phi$ vanishes.

By analyzing the height of the first peak and its left-hand width, we showed [13] that the peak approaches a δ function as $\Delta \phi$ decreases toward zero. We have since obtained more systems over a wider range of $\Delta \phi$. Figure 2 shows the dependence on $\Delta \phi$ of the first-peak height $g(r_{\text{peak}})$ and its lefthand width w_L for both harmonic and Hertzian potentials. Independent of the interaction potential, we find

$$g(r_{\text{peak}}) \sim \Delta \phi^{-1.0},\tag{1}$$

$$w_L \sim \Delta \phi^{1.0}.$$
 (2)

These scalings are consistent with the area of the peak approaching a constant in the limit $\Delta \phi \rightarrow 0$.

We turn now to the shape of the first peak in g(r) at r < 1 for a system at $\Delta \phi = 1 \times 10^{-6}$, just above the jamming transition. As shown in Fig. 3(a), for the region r < 1, g(r) is



FIG. 3. Pair distribution function g(r) up to contact 0 < r < 1 on a linear-logarithmic scale, for $\Delta \phi =$ (a) 10^{-6} , (b) 10^{-4} , (c) 10^{-2} , and (d) 10^{-1} .

almost strictly exponential with only a small curvature near its peak. It can be fitted with the functional form

$$g(r < \sigma) = g_0 \exp\left[-\left(\frac{\alpha_1}{\delta} + \frac{\alpha_2^2}{\delta^2}\right)^{-1}\right]$$
(3)

where $\delta \equiv 1 - r/r_{\text{peak}}$, with $\alpha_1 = 1.4 \times 10^{-7}$ and $\alpha_2 = 1.2 \times 10^{-7}$.



FIG. 4. Evolution of the parameters α_1 and α_2 (top) and g_0 (bottom) in Eq. (3) with $\Delta \phi$, for harmonic repulsions. The parameters $\alpha_{1,2}$ are clearly related to the pressure, while g_0 is associated with $g(r_{\text{peak}})$.

As we compress the system above ϕ_c we see that the exponential behavior of the tail at r < 1 gradually becomes more Gaussian as the system is compressed above the transition. This is shown in Figs. 3(a)-3(d). We can still use Eq. (3) to fit the shape, but with different coefficients α_1 and α_2 . In Fig. 4 we show the evolution of α_1 and α_2 with $\Delta \phi$. This evolution occurs more rapidly for Hertzian (not shown) than for harmonic spheres.

The results for g(r < 1) have implications for the distribution P(F) of interparticle normal forces F. This is shown in Fig. 5. At high compressions, P(F) is well described by a Gaussian, but the tail straightens out toward an exponential as $\Delta \phi$ is lowered toward zero. These results are consistent with previous results of Makse et al. [16,24], who studied sphere packings at fixed pressure. (As we noted above, constant pressure corresponds to constant $\Delta \phi$.) The Gaussian shape at high $\Delta \phi$ is consistent with expectations for equilibrium systems interacting with a harmonic potential [25]. However, these systems are at zero temperature, and it is unclear whether they can be described by a nonzero effective temperature. The exponential behavior at small $\Delta \phi$ agrees with experimental and simulation data on static granular packings of hard particles, which necessarily exist at packing fractions near ϕ_c [16,26,27].

There is interesting behavior above the asymmetric first peak in g(r) as well as below it. Figure 6(a) shows that g(r>1) versus r-1 varies as a power law for a system just above the transition at $\Delta \phi = 10^{-8}$:



FIG. 5. The distribution of normal contact forces, P(F), for the purely repulsive, harmonic potential, at different compressions $\Delta \phi$.



FIG. 6. Behavior just above the first-neighbor peak for a system at $\Delta \phi = 10^{-8}$. (a) g(r > 1) versus r-1. A power law with exponent of -0.5 is indicated. (b) $Z(\ell)$ vs $\ell \equiv r-1$, computed by numerically integrating g(r) > 1. A power law with exponent of 0.5 is indicated.

$$g(r > 1) \propto (r - 1)^{-\eta}$$
 (4)

with η =0.48±0.03. This result was first reported for gravitysedimented, granular packings [28], but over a much smaller range in g(r) than presented here. We note that there is a very slight knee that occurs near $r-1=3 \times 10^{-2}$. The asymptotic power-law behavior near r=1 should be determined only from the region below this knee. As we will show below, this knee becomes more pronounced as $\Delta \phi$ increases.

The number of neighbors $Z(\ell)$ that are separated by a distance of at most ℓ [29] is given by the integral

$$Z(\ell) = 24\phi \int_0^\ell g(r') r'^2 dr'.$$
 (5)

This is shown in Fig. 6(b). Therefore, Fig. 6(a) and Eq. (4) imply that for a system at the transition, Z should increase with ℓ as

$$Z - Z_{\text{contact}} \sim \ell^{1 - \eta = 0.52 \pm 0.03}$$
 (6)

where η is defined in Eq. (4) and $Z_{\text{contact}}=5.88$ is the average number of neighbors per particle at contact at the transition. This scaling is consistent with the one reported by O'Hern *et al.* [12], who looked at how the excess coordination number increased as a system was incrementally compressed above ϕ_c . We note that we have found a similar exponent of 0.50 ± 0.03 using the Hertzian interaction potential, $\alpha=2.5$, as we found for the harmonic potential, $\alpha=2$. Donev *et al.* [30] also calculated the number of neighbors $Z(\ell)$ near the transition, but for a system of hard spheres. When they plotted $\log_{10}[Z(\ell)-Z_c]$ versus $\log_{10} \ell$ they found that the slope was closer to 0.6 than 0.5. They argued that this implies that $g(r>1) \propto (1-r)^{-0.4}$ for hard spheres, which is different from our result for soft repulsive spheres [Eq. (6)]. Based on this difference, they concluded that the power-law behavior seen for $r>r_{peak}$ is not universal and depends on the interparticle potential as well as perhaps the procedure leading to the T=0 configuration.

However, that conclusion does not follow from their analysis. The confusion occurs because their results were for a system in which all the rattlers (that is, particles without any neighbors) had been removed. It is not surprising that this changes the nature of the pair correlation function from a system, such as ours, where all particles are considered. That is, we analyze the system directly as produced by energy minimization without performing the additional step of removing particles that do not happen to be part of the backbone of the structure. Whether one chooses to remove rattlers or not depends on the physics one wants to study. Here we remark that it is more natural to include rattlers in g(r) if one is going to compare to any experiment. We also note that rattlers can join the backbone when the system is perturbed, and can therefore influence the system's response and stability, as argued in Ref. [31]. Finally, we claim that the conclusion of Donev et al. that the power-law exponent depends on the potential of interaction or the algorithm for creating the states (aside from removing one class of particles by hand) is unfounded. Rather, the difference arises from whether one studies systems with rattlers included or removed. When Donev et al. include rattlers in their analysis, they also find an exponent closer to 0.5 [32], consistent with what we have found here and in previous work [12,13,28].

There is a difference between Z_c and $Z_{contact}$. Z_c is the number of contacts only for a system that has all rattlers removed from the system. If the rattlers are not removed from the system then $Z_{contact} \leq Z_c$. Because g(r), for example, measured in an experiment, does not distinguish between rattlers and particles belonging to the connected backbone of the structure, one must use $Z_{contact} \approx 5.88$ in Eqs. (6). Indeed, calculating $Z(\ell)$ either directly as in Ref. [30] or by integrating g(r) via Eq. (5) are identical only when using $Z_{contact}=5.88$ and not $Z_c=6$ in Eq. (6). If N denotes the total number of particles, $N_{overlaps}$ the number of overlapping pairs, and N_f the total number of rattlers, then $Z_{contact} = 2N_{overlaps}/N$ while $Z_c=2N_{overlaps}/(N-N_f)$. Although only 2% of the particles are rattlers at the transition, their exclusion can produce a change of the power-law exponent.

We find that the observed power law for g(r) depends on $\Delta\phi$ [see Fig. 7(a)]. As $\Delta\phi$ increases, the knee in g(r) near $r-1 \approx 3 \times 10^{-2}$ becomes more prominent. In the region below this knee (i.e., at smaller *r*), the slope of $\log_{10}[g(r)]$ versus $\log_{10}(r-1)$ decreases. We show this slope η as a function of $\Delta\phi$ in Fig. 7(b). As $\Delta\phi$ approaches zero, the value of η increases and approaches $\eta=0.5$. A similar trend was noted in the x-ray tomography experiments of Aste *et al.* [33–35], who measured g(r) inside large, three-dimensional granular packings. Note that Donev *et al.* [30] study configurations



FIG. 7. Pair distribution function g(r), just above the first peak for $\Delta \phi = 10^{-8}$ (×), 10^{-6} (circles), 10^{-4} (squares), 10^{-3} (diamonds), 10^{-2} (+). (a) g(r) vs r-1, showing the power-law behavior in (r-1). (b) The exponent η characterizing the power-law behavior of (a), as a function of $\Delta \phi$. (c) g(r) from the nearest-neighbor, first peak at r_{peak} out to the first minimum at $r \approx 1.4$ as a function of $r-r_{\text{peak}}$.

below the unjamming transition, and it is not clear if the apparent value of η also changes as the density is decreased below ϕ_c . Figure 7(c) shows, for different values of $\Delta \phi$, how g(r) behaves in the region from $r=r_{\text{peak}}$ out to the first minimum at $r \approx 1.4$. There are several notable features in g(r) in the vicinity of contact that are apparent when g(r) versus $(r-r_{\text{peak}})$ is plotted on log-log axes. There is a drop in g(r)that occurs at r=1 for each value of $\Delta \phi$ (note that this corresponds to different values of $r - r_{peak}$ for different $\Delta \phi$). The separation r=1 distinguishes particles that are overlapping from those which are just out of contact. The magnitude of the jump decreases, and the extent of the power-law region described by Eq. (4) also decreases, as the system is progressively compressed above the unjamming transition. The region beyond contact is relatively unaffected by compression. [Although the power-law exponent changes slowly with $\Delta \phi$ as highlighted in Fig. 7(b), by far the largest change occurs in crossing from r < 1 to r > 1. This indicates that as the system is compressed, particles are depleted from the region beyond contact, r > 1, and are absorbed into the contact region, r < 1.



FIG. 8. Pair distribution function g(r), from the nearestneighbor, first peak at r_{peak} out to the first minimum at $r \approx 1.4$, at $\Delta \phi = 10^{-4}$. Different symbols represent different configuration protocols with and without temperature: conjugate gradient minimization to T=0 (open circles), quenched molecular dynamics at T=0(open squares), molecular dynamics at a very low temperature (solid diamonds), and molecular dynamics at a higher temperature (+). The jump in g(r) persists to small but nonzero temperature, and is smoothed out at high enough temperatures.

We have determined that this drop in g(r) is not an artifact of the zero-temperature system. We have used several different protocols for creating particle configurations, as shown in Fig. 8 and described in its caption. Evidently, the drop in g(r)persists to finite temperature.

Why should there be an abrupt drop in g(r) at r=1? One possibility is that, to a first approximation, compression only changes the nearest-neighbor spacing of particles that are already in contact, that is, within a distance r<1 of each other. Particles separated by a distance r>1 may not be moved appreciably closer to one another by compression. Instead, we suggest that upon compression, the movement of particles that are not yet overlapping is predominantly in a direction perpendicular to the line connecting them. This is consistent with our data.

As the system is compressed and particles are incorporated into the contact region, the number of overlapping pairs increases. As mentioned above, the average number of overlapping neighbors per particle, Z, increases with compression as $Z-Z_{\text{contact}} \propto \Delta \phi^{0.5}$. As this occurs, the distribution of Z values, P(Z), also shifts. This is shown in Fig. 9. Close to the



FIG. 9. The distribution P(Z) of the number of overlapping neighbors per particle, Z, at several different compressions. Key same as Fig. 5.



FIG. 10. g(r) region around the split second peak for $\Delta \phi = (a)$ 10⁻⁶, (b) 10⁻³, and (c) 10⁻¹.

transition, most particles have six overlapping neighbors, as do granular packings [24,28]. As the system is compressed to $\Delta \phi = 0.1$, the maximum shifts to Z=9 but there is still no observable weight at Z=12, and the behavior is similar to the properties of compressed emulsions [23,24].

III. SPLIT SECOND PEAK OF g(r)

The approach of the unjamming point is also apparent in features associated with the second peak in g(r). Figure 10 shows this region of g(r) for several values of $\Delta \phi$. For the system closest to jamming, at $\Delta \phi = 1 \times 10^{-6}$ [Fig. 10(a)], there is a pronounced splitting of the second peak in g(r) into two subpeaks, located at $r = \sqrt{3}$ and 2. Such a splitting of the second peak has long been known [1,9,36]. Indeed, the emergence of a split second peak was one of the early criteria used to signal the onset of the glass phase in supercooled liquids, and is generally accepted as lore, indicating the emergence of the amorphous state.

On the small-*r* side of both of these subpeaks we find that g(r) increases rapidly. In Fig. 11, we have attempted to characterize these features for the system closest to the transition. In that figure we plot g(r) versus $\log_{10}(\sqrt{3}-r)$ and $\log_{10}(2-r)$. We have not been able to tell whether g(r) itself diverges or whether the divergence appears only in its slope dg(r)/dr. We would need to average over many more systems to tell these two possibilities apart unambiguously. Our best fits to the two possible cases are

$$g(r) = a_1(\sqrt{3} - r)^{-a_2},\tag{7}$$

$$g(r) = g(\sqrt{3}) - b_1(\sqrt{3} - r)^{b_2},$$
(8)

$$g(r) = -c_1 \log_{10}(\sqrt{3} - r) \tag{9}$$

and

$$g(r) = d_1(2 - r)^{-d_2},$$
(10)

$$g(r) = g(2) - e_1(2 - r)^{e_2},$$
(11)

$$g(r) = -f_1 \log_{10}(2 - r), \qquad (12)$$



FIG. 11. Functional form of the subpeaks of the split second peak in g(r) for $\Delta \phi = 10^{-6}$. Left-hand subpeak at $r = \sqrt{3}$; right-hand subpeak at r=2. The solid line corresponds to a power-law fit, the dashed line to a logarithmic fit, and the gray line to a shifted power-law fit.

where the fit parameters are provided in Table I.

On the high-*r* side of each subpeak, it is clear from Fig. 10(a) that there is both a step-function drop-off [30,37] and an additional smooth decrease of g(r) with increasing *r*. Although, from these data, we cannot unambiguously determine a functional form for this last smooth decrease, the data suggest that it might be fitted with

$$g(r) = a - (r - r_s)^b,$$
 (13)

where 0 < b < 1 and $r_s = \sqrt{3}$ and 2 for the first and second subpeaks, respectively. As the system is compressed above the transition, the structure around both subpeaks becomes rounded. In particular, it is only in the limit of $\Delta \phi \rightarrow 0$ that the drop-off becomes a sharp step function.

The local particle arrangements contributing to the subpeaks that make up the split second peak have been investigated [7,38]. Our focus here is a simple interpretation of the

TABLE I. Fit parameters for the two subpeaks, situated at $r = \sqrt{3}$ and 2, respectively, that make up the split second peak in g(r). For $\Delta \phi = 10^{-6}$.

First subpeak	Second subpeak
<i>a</i> ₁ =0.9	$d_1 = 1.1$
$a_2 = 0.12$	$d_2 = 0.08$
<i>b</i> ₁ =2.75	<i>e</i> ₁ =2.8
<i>b</i> ₂ =0.16	<i>e</i> ₂ =0.12
<i>c</i> ₁ =0.25	$f_1 = 0.15$



FIG. 12. Left: The particles at the left and at the right share two common neighbors and are separated by a distance $r=\sqrt{3}$. Right: The particles at the left and the right share one common neighbor and are separated by r=2.

origin of the step-function drop-off in g(r) on the high-r side of both subpeaks. At the jamming transition, each particle must be held in place by particles that are just in contact with no overlap. At that point there is an average of precisely $Z_c=6$ neighbors per particle in the force network. It seems plausible that the second-nearest-neighbor peaks originate from pairs of particles that have at least one neighbor in common, while pairs that do not have a common neighbor contribute only to a slowly varying background.

The separation r=2 corresponds to two particles on diametrically opposite sides of a common neighbor (Fig. 12, right). This is the largest distance that can separate two particles that have one common neighbor. The separation $r=\sqrt{3}$ corresponds to the largest possible separation between two particles *i* and *j* that have two common neighbors (Fig. 12, left). In this case the four particles lie in the same plane; the two common neighbors touch and the particles *i* and *j* are on opposite sides of the crease between them. When *r* is only slightly greater than 2, there can no longer be any contribution from two particles that share a common neighbor. Similarly, when *r* is only slightly greater than $\sqrt{3}$, there can be no contribution from pairs of particles that share two common neighbors. This leads to step-function drop-offs at $r=\sqrt{3}$ and 2.

Support for the hypothesis that the drop-offs are due to pairs of particles that share common neighbors can be obtained from the angular correlations between two neighbors of a common particle. We show this angular correlation $P(\theta)$ in Fig. 13, where θ is defined in the sketch in the inset. At $\theta = \pi$ (which corresponds to particles separated by r=2) Fig. 13(d) shows that the distribution goes to zero as

$$P(\theta) \sim (\pi - \theta)^{x=0.75}.$$
 (14)

If the subpeak at r=2 arises from pairs that share one common neighbor, then the form of g(r) just below r=2 should be related to the form of $P(\theta)$ just below $\theta=\pi$ by

$$g(r) = P(\theta)d\theta/dr \tag{15}$$

where the Jacobian factor diverges as

$$d\theta_{i,j}/dr = \frac{1}{\cos(\theta_{i,j}/2)} = \frac{2}{\sqrt{4 - r^2}}.$$
 (16)

Thus, Eq. (15) implies

$$g(r) \sim (2-r)^{(x-1)/2=-0.12}.$$
 (17)

This is in reasonable agreement with the fit in Eq. (11), where we found $g(r) \sim (2-r)^{-d_2=-0.08}$, implying that the sec-



FIG. 13. (a) The three-particle angular correlation $P(\theta_{i,j})$ versus $\theta_{i,j}$ for $\Delta \phi = 10^{-6}$. Bottom four panels are fits to the regions around $\theta =$ (b) 60°, (c) 120° left, (d) 120° right, and (e) 180°. The power-law exponents are $\approx 0.5, 0.17, 0.17, and 0.75$, respectively.

ond subpeak does indeed arise from two particles that share a common neighbor and that this leads to the observed stepfunction drop-off just above r=2. However, we should note that this argument does not necessarily imply that g(r) diverges at r=2, as indicated by Eq. (17), since we cannot determine the behavior of $P(\theta)$ asymptotically close to π with sufficient accuracy.

By a similar argument, if the first subpeak arises from pairs of particles that share two common neighbors, then the peak at $r = \sqrt{3}$ corresponds to $\theta = 2\pi/3$. For $\theta < 2\pi/3$, we find

$$P(\theta) \sim (2\pi/3 - \theta)^{-0.17}.$$
 (18)

This behavior implies $g(r) \sim (\sqrt{3} - r)^{-0.17}$; this result is not too different from the fit in Eq. (7), which suggests $g(r) \sim (\sqrt{3} - r)^{-0.12}$. This consistency check suggests that the first subpeak does indeed arise from pairs of particles that share two common neighbors.

Although pairs with two common neighbors cannot contribute to g(r) for $r > \sqrt{3}$, pairs with only one common neighbor can still contribute. Such pairs may account for the smooth decrease in g(r) [see Eq. (13)] just above $r = \sqrt{3}$.

IV. DISCUSSION

We have shown that the unjamming transition is accompanied by several features in the pair correlation function.

(1) A δ function at r=1 with area $Z_{\text{contact}} < 6$.

(2) A power law at $r \ge 1$ of the form $g(r) \sim (r-1)^{-0.5}$.

(3) A subpeak at $r = \sqrt{3}$ that either diverges or has diverging slope as $r \to \sqrt{3}^-$ and that has a step-function drop-off just above $r = \sqrt{3}$.

(4) A subpeak at r=2 that either diverges or has diverging slope as $r \rightarrow 2^-$ and that has a step-function drop-off just above r=2.

These features appear for both the short-ranged and purely repulsive harmonic and Hertzian potentials studied here, and therefore seem to be purely geometrical features of the jamming-unjamming transition at zero temperature.

Here, we suggest that some of these structural features are reflected in a less extreme form in the two primary empirical criteria that have been used extensively in the literature to identify the glass transition. We expect these features to become increasingly prominent as the short-range repulsive part of the interaction potential plays a more dominant role in determining structure. The first is the ratio \mathcal{R} of the first minimum to the first maximum in g(r). As the temperature T of a glass-forming liquid decreases, \mathcal{R} decreases. Wendt and Abraham [2] proposed that $\mathcal{R}=0.14$ corresponds to a reasonable estimate of the glass transition temperature T_g . We note that at the unjamming transition we have studied here, $\mathcal{R}=0$. It is possible that the decrease in \mathcal{R} observed as T is lowered toward T_{g} is a remnant of the vanishing of \mathcal{R} that occurs at the unjamming transition. The latter property may be the underlying reason for the apparent success of this empirical criterion in the case of molecular [2,3] as well as colloidal [39] glasses.

A second popular empirical criterion concerns the second peak of g(r). As T is lowered toward T_g , the second peak splits into two subpeaks. The flattening of the second peak that signals its splitting has been used to identify T_g [2]. The splitting of the second peak has also been observed during the transition from the flowing to the stopped state in a granular material [40]. We suggest that the splitting may reflect the singular subpeaks that occur at jamming-unjamming transition. The singular nature of the splitting at this transition may provide the fundamental underpinnings of this criterion.

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